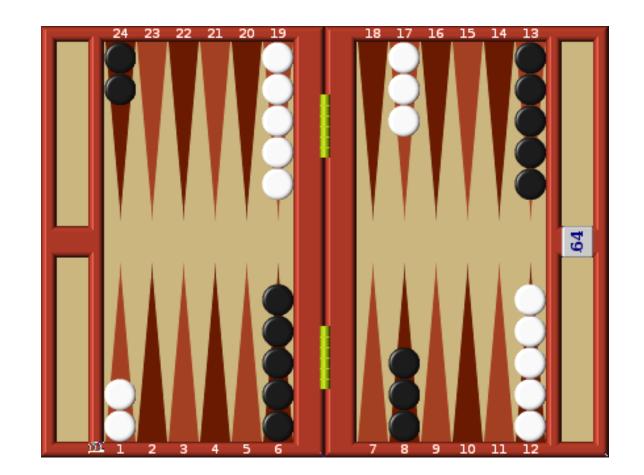
Stochastic Search



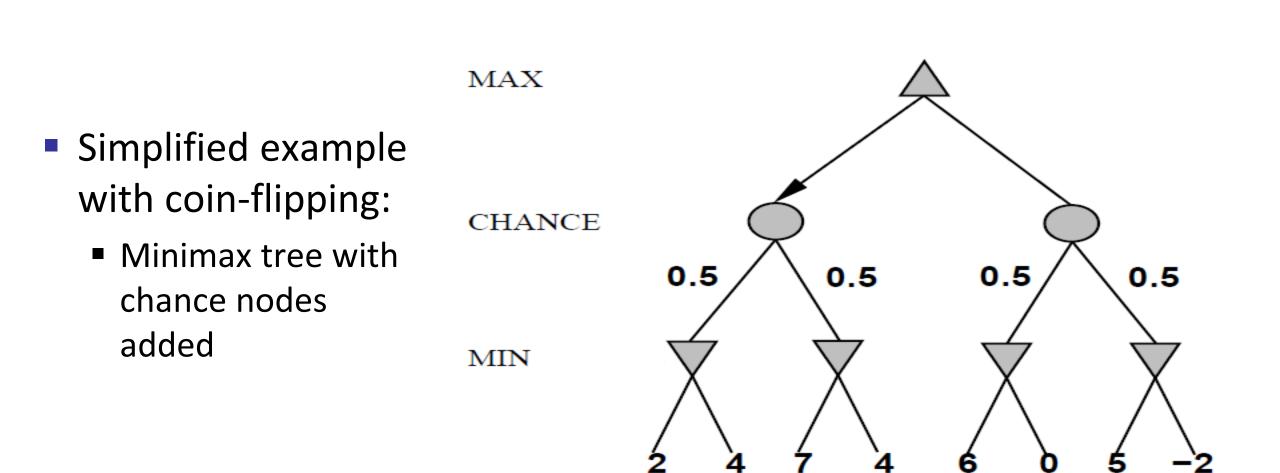
[These slides were created by Dan Klein and Pieter Abbeel for CS188 Intro to AI at UC Berkeley. All CS188 materials are available at http://ai.berkeley.edu.]

Nondeterministic Games

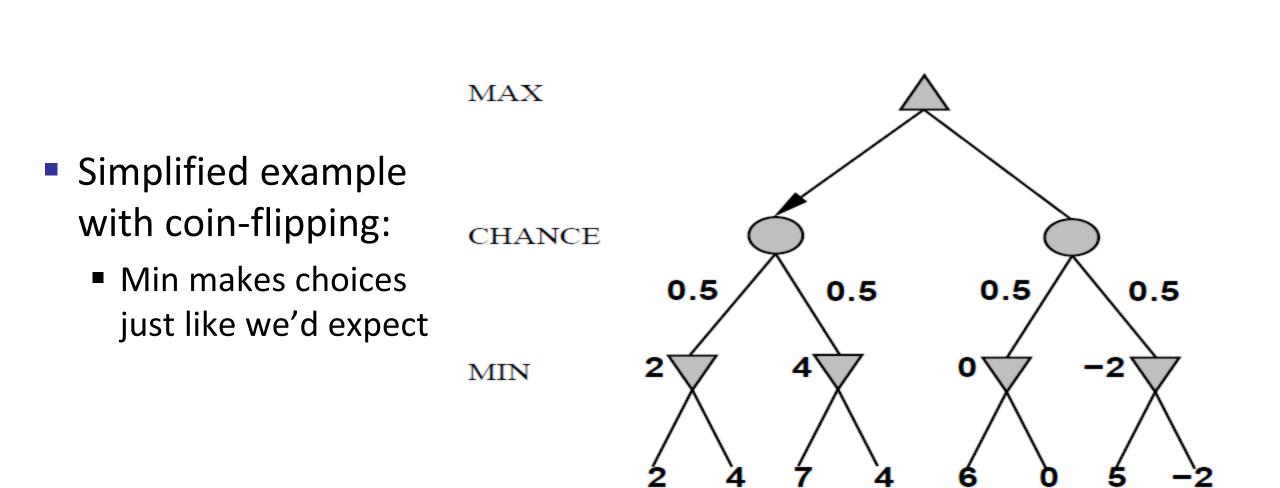
 In nondeterministic games, chance introduced by dice, card-shuffling



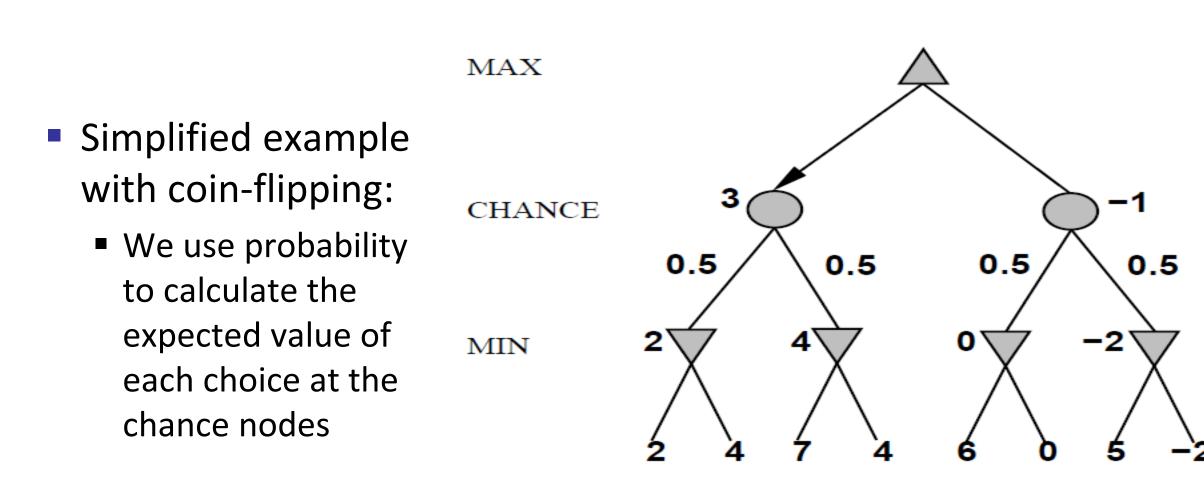
Nondeterministic Games in General



Nondeterministic Games in General



Nondeterministic Games in General



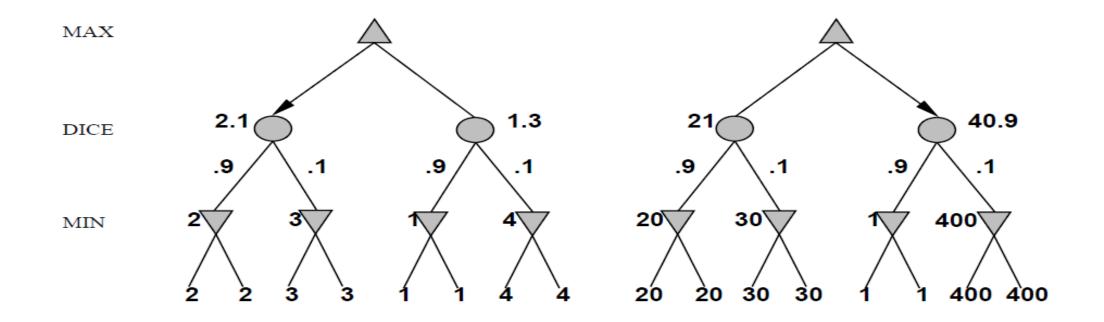
Expectiminimax is just like Minimax, except we must also handle chance nodes:

if state is a MAX node then
 return the highest EXPECTIMINIMAX-VALUE of SUCCESSORS(state)
if state is a MIN node then
 return the lowest EXPECTIMINIMAX-VALUE of SUCCESSORS(state)
if state is a chance node then
 return average of EXPECTIMINIMAX-VALUE of SUCCESSORS(state)

. . .

- Dice rolls increase branching factor: 21 possible rolls with 2 dice
- Backgammon ~ 20 legal moves
 - Depth 4 = 20 x (21 x 20)³ ~ 1.2 x 10⁹
- As depth increases, probability of reaching a given node shrinks
 - Value of lookahead is seriously diminished
- α-β pruning is much less effective
- TDGammon uses depth-2 search + very good Eval
 - World-champion level

- Behavior is preserved only by positive linear transformation of Eval
- Hence Eval should be proportional to the expected payoff



- E.g., card games, where opponent's initial cards are unknown
- Typically we can calculate a probability for each possible deal
- Seems just like having one big dice roll at the beginning of the game
- Idea: compute the minimax value of each action in each deal, then choose the action with highest expected value over all deals
- Special case: if an action is optimal for all deals, it's optimal.
- GIB, current best bridge program, approximates this idea by
 - 1) generating 100 deals consistent with bidding information
 - 2) picking the action that wins most tricks on average
 - "On average" as determined by Monte Carlo simulation, not a calculated expected value



Commonsense Example

- Day 1: Deterministic
 - Road A leads to a small heap of gold pieces (Eval = \$1,000)
 - Road B leads to a fork:
 - take the left fork and you'll find a mound of jewels; (Eval = \$1,000,000)
 - take the right fork and you'll be run over by a bus.







Commonsense Example

- Day 1: Deterministic
 - Road A leads to a small heap of gold pieces (Eval = \$1,000)
 - Road B leads to a fork:
 - take the left fork and you'll find a mound of jewels; (Eval = \$1,000,000)
 - take the right fork and you'll be run over by a bus.
- Day 2: Deterministic
 - Road A leads to a small heap of gold pieces (Eval = \$1,000)
 - Road B leads to a fork:
 - take the left fork and you'll be run over by a bus;
 - take the right fork and you'll find a mound of jewels. (Eval = \$1,000,000)











Commonsense Example

- Day 1 Deterministic:
 - Road A leads to a small heap of gold pieces (Eval = \$1,000)
 - Road B leads to a fork:
 - take the left fork and you'll find a mound of jewels; (Eval = \$1,000,000)
 - take the right fork and you'll be run over by a bus. CAUTION
- Day 2 Deterministic:
 - Road A leads to a small heap of gold pieces (Eval = \$1,000)
 - Road B leads to a fork:
 - take the left fork and you'll be run over by a bus;
 - take the right fork and you'll find a mound of jewels. (Eval = \$1,000,000)
- Day 3 Stochastic (50/50 chance on the road B fork):
 - Road A leads to a small heap of gold pieces (Eval = \$1,000)
 - Road B leads to a fork:
 - guess correctly and you'll find a mound of jewels; (Eval = \$1,000,000)
 - guess incorrectly and you'll be run over by a bus.





- Intuition that the value of an action is the average of its values in all actual states is WRONG
- With partial observability, value of an action depends on the information state or belief state the agent is in
- Can generate and search a tree of information states
- Leads to rational behaviors such as
 - Acting to obtain information
 - Signaling to one's partner
 - Acting randomly to minimize information disclosure
 - Cooperation and/or alliances



- Games are fun to work on! (and dangerous)
- They illustrate several important points about AI
 - Perfection is unattainable => must approximate
 - Good idea to think about what to think about
 - Uncertainty constrains the assignment of values to states
 - Optimal decisions depend on information state, not real state

Semester Project

- In the past weeks we've talked about characteristics of agents and of environments
- We've seen the effect of nondeterminism and partial observability on search efforts
- With these in mind, it's time to start talking about what we want to choose for the semester project

